

276(S): Development of Thomas Precession Theory

The three dimensional metric case with τ as:

$$ds^2 = c^2 d\tau^2 = c^2 dt^2 - r^2 d\beta^2 - dr^2 \quad (1)$$

where $d\beta^2 = d\theta^2 + \sin^2 \theta d\phi^2 \quad (2)$

The velocity is defined by:

$$v^2 = r^2 \left(\left(\frac{d\theta}{dt} \right)^2 + \sin^2 \theta \left(\frac{d\phi}{dt} \right)^2 \right) \quad (3)$$

$$= r^2 \left(\frac{d\beta}{dt} \right)^2$$

The two dimensional metric is:

$$ds^2 = c^2 d\tau^2 = c^2 dt^2 - dr^2 - r^2 d\phi^2 \quad (4)$$

and the two dimensional Thomas precession is defined

by:

$$\phi' = \phi + \omega t \quad (5)$$

so the one dimensional analogy is:

$$\beta' = \beta + \omega t \quad (6)$$

As shown in UFT 265 eq. (5) results in:

$$ds^2 = c^2 d\tau^2 = \left(1 - \frac{3v_0^2}{c^2} \right) c^2 dt^2 - v^2 dt^2 \quad (7)$$

$$= \left(1 - \frac{6MG}{c^2 r} \right) c^2 dt^2 - v^2 dt^2$$

Therefore:

$$c^2 d\tau^2 \left(1 - \frac{6mG}{c^2 r}\right)^{-1} = c^2 dt^2 - v^2 \left(1 - \frac{6mG}{c^2 r}\right)^{-1} \quad (8)$$

Therefore the proper time is increased by a factor of:

$$\tau' = \tau \left(1 - \frac{6mG}{c^2 r}\right)^{-1/2} \quad (9)$$

$$\sim \tau \left(1 + \frac{3mG}{c^2 r}\right)$$

and the total velocity v is increased by:

$$v' = v \left(1 - \frac{6mG}{c^2 r}\right)^{-1/2} \quad (10)$$

$$\sim v \left(1 + \frac{3mG}{c^2 r}\right)$$

The velocity v is also the classical velocity, so denoting:

$$x = 1 + \frac{3mG}{c^2 r} \quad (11)$$

The Hamiltonian is changed to:

$$H' = E' = \frac{1}{2} m x^2 \left(\left(\frac{dr}{dt} \right)^2 + r^2 \left(\frac{d\phi}{dt} \right)^2 \right) - \frac{k}{r} \quad (12)$$

compared with the original:

$$H = E = \frac{1}{2} m \left(\left(\frac{dr}{dt} \right)^2 + r^2 \left(\frac{d\phi}{dt} \right)^2 \right) - \frac{k}{r} \quad (13)$$

3) The Lagrangian is changed to:

$$L' = \frac{1}{2} m \dot{r}^2 \left(\left(\frac{dr}{dt} \right)^2 + r^2 \left(\frac{d\phi}{dt} \right)^2 \right) + \frac{k}{r} \quad - (14)$$

compared with the original:

$$L = \frac{1}{2} m \left(\left(\frac{dr}{dt} \right)^2 + r^2 \left(\frac{d\phi}{dt} \right)^2 \right) + \frac{k}{r} \quad - (15)$$

From the Euler Lagrange equation:

$$\frac{\partial L}{\partial \phi} = \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{\phi}} \right) \quad - (16)$$

The angular velocity from eq. (15) is:

$$\frac{d\phi}{dt} = \frac{L}{mr^2} \quad - (17)$$

and using $\frac{dr}{dt} = \frac{dr}{d\phi} \frac{d\phi}{dt}$ $- (18)$

eq. (13) becomes:

$$E = \frac{1}{2} \frac{L^2}{mr^4} \left(\left(\frac{dr}{d\phi} \right)^2 + r^2 \right) - \frac{k}{r} \quad - (19)$$

$$\therefore \left(\frac{dr}{d\phi} \right)^2 = \left(\frac{2mE}{L^2} \right) r^4 - r^2 + \left(\frac{2mk}{L^2} \right) r^3 \quad - (20)$$

Eq. (20) is also given by the ellipse:

$$r = \frac{d}{1 + E \cos \phi} \quad - (21)$$

4) This follows from:

$$\frac{dr}{d\phi} = \frac{\epsilon}{d} r^2 \sin \phi \quad - (22)$$

so
$$\left(\frac{dr}{d\phi} \right)^2 = \frac{\epsilon}{d} r^2 (1 - \cos^2 \phi) \quad - (23)$$

where
$$\cos^2 \phi = \frac{1}{\epsilon^2} \left(\frac{d}{r} - 1 \right)^2 \quad - (24)$$

It follows that:

$$\left(\frac{dr}{d\phi} \right)^2 = \frac{r^4}{d^2} (\epsilon^2 - 1) - r^2 + \frac{2r^3}{d} \quad - (25)$$

which is eq. (20) provided that:

$$\frac{\epsilon^2 - 1}{d^2} = \frac{2mE}{L^2} \quad - (26)$$

and
$$d = \frac{L^2}{mk} \quad - (27)$$

When v is replaced by xv , eq. (16)

gives:

$$\frac{d}{dt} \left(x^2 m r^2 \frac{d\phi}{dt} \right) = 0 \quad - (28)$$

so the conserved angular momentum is changed to:

$$L \rightarrow x^2 L = L' \quad - (29)$$

Therefore:

$$5) \quad \frac{d\phi}{dt} = \frac{L}{mr^2 x^2} - (30)$$

$$\text{and } E = \frac{1}{2} m x^2 \left(\frac{dr}{dt} \right)^2 \left(\left(\frac{dr}{d\phi} \right)^2 + r^2 \right) - \frac{k}{r}$$

$$= \frac{1}{2} \frac{L^2}{mr^4 x^2} \left(\left(\frac{dr}{d\phi} \right)^2 + r^2 \right) - \frac{k}{r} \quad (31)$$

$$\text{So: } \left(\frac{dr}{d\phi} \right)^2 = \left(\frac{2mE}{x^2 L^2} \right) r^4 - r^2 + \left(\frac{2mk}{x^2 L^2} \right) r^3 - (32)$$

Now consider the precessing ellipse:

$$r = \frac{d}{1 + \epsilon \cos(x\phi)} \quad (33)$$

It follows that:

$$\frac{dr}{d\phi} = \left(\frac{\epsilon x c}{d} \right) r^2 \sin(x\phi) \quad (34)$$

$$\text{and } \left(\frac{dr}{d\phi} \right)^2 = \frac{\epsilon^2 x^2}{d^2} r^4 \left(1 - \cos^2(x\phi) \right) \quad (35)$$

where

$$\cos(x\phi) = \frac{1}{\epsilon} \left(\frac{d}{r} - 1 \right) \quad (36)$$

$$\text{So: } \left(\frac{dr}{d\phi} \right)^2 = \frac{x^2 (\epsilon^2 - 1)}{d^2} r^4 - x^2 r^2 + \frac{2x^2}{d} r^3 \quad (37)$$

6) Eqs. (32) and (37) are the same if:

$$\frac{x^2 (\epsilon^2 - 1)}{d^2} = \frac{2mE}{x^2 L^2}, \quad - (38)$$

$$\frac{mk}{x^2 L^2} = \frac{x^2}{d} \quad - (39)$$

and $xr \sim r \quad - (40)$

Under conditions (38) to (40) the 2D Thomas precession gives the precessing elliptical orbit, QED.

By experimental observation:

$$x = 1 + \frac{3MG}{c^2 d} \quad - (41)$$

so $x = \left(1 + \frac{3MG}{c^2 r}\right)_{r=d} \quad - (42)$

The condition $r = d \quad - (43)$

means that

$$m \frac{d^2 r}{dt^2} = \frac{dV(r)}{dr} = 0 \quad - (44)$$

where the effective potential is:

$$V(r) = -\frac{mmG}{r} + \frac{L^2}{2mr^2} \quad - (45)$$

7) Under condition (45) and (44) the mass m behaves as if it is a free mass or free particle, and this is consistent with the fact that the starting metric is that of a free particle.

So the 2D Thomas precession gives the precessing ellipse:

$$r = \frac{d}{1 + \epsilon \cos(x\phi)} \quad - (46)$$

where

$$x = 1 + \frac{3MG}{c^2 d} \quad - (47)$$

This theory must now be developed in three dimensions.
